# Stationary Probability Distributions of a Markov Chain

Berlian Setiawaty

Department of Mathematics, Bogor Agricultural University Jl. Raya Pajajaran Bogor, 16144 Indonesia

### Abstract

This article shows that stationary probability distributions of a Markov chain can be classified into two classes. These classes are determined by the type of communicating classes of the chain.

Keywords : Markov chain, Stationary probability distributions, Communicating classes

### 1 Introduction

The aim of this article is to show the relations between communicating classes and stationary probability distributions of a Markov chain. By analysing the type of the communicating classes of the chain, we will show that stationary probability distributions can be classified into two classes.

In section 2, definitions and basic result regarding Markov chain are given. The main result of the article is presented in section 3.

### 2 Markov Chains

Let  $\{X_t : t \in N\}$  be a sequence of random variables defined on a probability space  $(\Omega, \mathcal{F}, P)$ , taking values in a finite set  $S = \{1, \ldots, K\}$ .  $\{X_t\}$  is said to be a *Markov* chain if it satisfies

$$P(X_{n+1} = i_{n+1} | X_1 = i_1, \dots, X_n = i_n) = P(X_{n+1} = i_{n+1} | X_n = i_n), \quad (1)$$

for all  $i_1, \ldots, i_{n+1} \in S$  and  $n \in N$ . Property (1) is called the *Markov property*.

25

Let  $m \leq n$ , then by (1),

$$P(X_{n+1} = i_{n+1} | X_1 = i_1, \dots, X_m = i_m)$$

$$= \sum_{i_{m+1}=1}^{K} \cdots \sum_{i_n=1}^{K} P(X_{m+1} = i_{m+1}, \dots, X_{n+1} = i_{n+1} | X_1 = i_1, \dots, X_m = i_m)$$

$$= \sum_{i_{m+1}=1}^{K} \cdots \sum_{i_n=1}^{K} \left\{ P(X_{m+1} = i_{m+1} | X_1 = i_1, \dots, X_m = i_m) \\ \times P(X_{m+2} = i_{m+2} | X_1 = i_1, \dots, X_{m+1} = i_{m+1}) \\ \times \cdots \times P(X_{n+1} = i_{n+1} | X_1 = i_1, \dots, X_n = i_n) \right\}$$

$$= \sum_{i_{m+1}=1}^{K} \cdots \sum_{i_n=1}^{K} \left\{ P(X_{m+1} = i_{m+1} | X_m = i_m) \cdot P(X_{m+2} = i_{m+2} | X_{m+1} = i_{m+1}) \\ \times \cdots \times P(X_{n+1} = i_{n+1} | X_n = i_n) \right\}$$

$$= \sum_{i_{m+1}=1}^{K} \cdots \sum_{i_n=1}^{K} P(X_{m+1} = i_{m+1}, \dots, X_{n+1} = i_{n+1} | X_m = i_m)$$

$$= P(X_{n+1} = i_{n+1} | X_m = i_m). \qquad (2)$$

So the Markov property (1) is equivalent with (2).

Assume that  $P(X_{n+1} = j | X_n = i)$  depends only on (i, j) and not on n. Let

$$\alpha_{ij} = P(X_{n+1} = j | X_n = i), \quad i, j = 1, 2, \dots, K,$$
(3)

then  $\alpha_{ij}$  are called the transition probabilities from state i to state j and the  $K\times K$  matrix A defined by

$$A = (\alpha_{ij}), \tag{4}$$

is called the transition probability matrix of the Markov chain  $\{X_t\}.$  Notice that A satisfies

$$0 \le \alpha_{ij} \le 1,$$
  $i, j = 1, ..., K$   
 $\sum_{i=1}^{K} \alpha_{ij} = 1,$   $i = 1, ..., K.$ 

Thus A is a stochastic matrix.

Let

$$\pi_i = P(X_1 = i), \quad i = 1, \dots, K$$
 (5)

and

$$\pi = (\pi_i). \tag{6}$$

The  $1 \times K$ -matrix  $\pi$  is called the *initial probability distribution* of the Markov chain  $\{X_t\}$ . Notice that  $\pi$  satisfies

$$0 \leq \pi_i \leq 1, \qquad i=1,\ldots,K \qquad \text{and} \qquad \sum_{i=1}^K \pi_i = 1.$$

By (1), (3), (4), (5) and (6),

$$P(X_{1} = i_{1}, ..., X_{n} = i_{n}) = P(X_{1} = i_{1}) \cdot P(X_{2} = i_{2}|X_{1} = i_{1})$$
$$\times \cdots \times P(X_{n} = i_{n}|X_{n-1} = i_{n-1})$$
$$= \pi_{i_{1}} \cdot \alpha_{i_{1}, i_{2}} \cdots \alpha_{i_{n-1}, i_{n}}.$$
(7)

Then by (7),

$$P(X_{n} = i) = \sum_{i_{1}=1}^{K} \cdots \sum_{i_{n-1}=1}^{K} P(X_{1} = i_{1}, \dots, X_{n-1} = i_{n-1}, X_{n} = i_{n})$$

$$= \sum_{i_{1}=1}^{K} \cdots \sum_{i_{n-1}=1}^{K} \pi_{i_{1}} \cdot \alpha_{i_{1}, i_{2}} \cdots \alpha_{i_{n-1}, i}$$

$$= \pi A^{n-1} e_{i}, \qquad (8)$$

where  $A^n = AA \cdots A$  and  $e_i = (0, \ldots, 0, 1, 0, \ldots, 0)^T$ . Hence, it can be concluded that the probability distribution of the Markov chain  $\{X_t\}$  is completely determined by the initial probability  $\pi$  and the transition probability matrix A.

If the initial probability distribution  $\pi$  satisfies

$$\pi A = \pi, \tag{9}$$

then  $\pi$  is called a *stationary probability distribution* with respect to A. By (8) and (9), for every  $n \in \mathbb{N}$ ,

$$P(X_n = i) = \pi A^{n-1} e_i$$
  
=  $\pi e_i$   
=  $\pi_i$ ,

implying

$$P(X_{m+1} = i_1, \dots, X_{m+n} = i_n) = P(X_{m+1} = i_1) \cdot P(X_{m+2} = i_2 | X_{m+1} = i_1)$$
  
 
$$\times \dots \times P(X_{m+n} = i_n | X_{m+n-1} = i_{n-1})$$
  
$$= \pi_{i_1} \cdot \alpha_{i_1, i_2} \cdots \alpha_{i_{n-1}, i_n}$$
  
$$= P(X_1 = i_1, \dots, X_n = i_n),$$

for  $m \in N$  and  $i_1, \ldots, i_n \in S$ . So in this case, the Markov chain  $\{X_t\}$  is *(strictly)* stationary.

To classify the states of the Markov chain  $\{X_t\}$ , define a *communication* relation " $\leftrightarrow$ " as follows. A state j is said to be *accessible* or reachable from a state i, denoted as  $i \rightarrow j$ , if there is an integer n,  $0 \le n < K$ , such that the (i, j) entry of  $A^n$  is positive. If  $i \rightarrow j$  and  $j \rightarrow i$ , then i and j are said to *communicate* with each other, denoted as  $i \leftrightarrow j$ .

For each state i, define a communicating class

$$C(i) = \{j \in S : i \leftrightarrow j\}.$$

Since relation  $\leftrightarrow$  is an equivalence relation, then the communicating classes satisfy :

(a). For every state  $i, i \in C(i)$ .

(b). If  $j \in C(i)$ , then  $i \in C(j)$ .

(c). For any state i and j, either C(i) = C(j) or  $C(i) \cap C(j) = \emptyset$ 

Thus the state space S can be *partitioned* into these classes.

A Markov chain is said to be *irreducible*, if all states communicate with each other. So in this case, the Markov chain has only one communicating class.

A communicating class C is called *ergodic* if

$$\sum_{j \in C} \alpha_{ij} = 1, \qquad \forall i \in C.$$
(10)

The individual states in an ergodic class are also called *ergodic*.

A communicating class C is called *transient*, if there is  $i \in C$ , such that

$$\sum_{j \in C} \alpha_{ij} < 1.$$
 (11)

The individual states in a transient class are also called *transient*.

To identify the transition probability matrix within a communicating class, the irreducibility of square matrix is introduced. An  $n \times n$ -matrix  $B = (\beta_{ij})$  is said to be *irreducible*, if there is a permutation of incices  $\sigma$ , such that the matrix  $\widetilde{B} = (\widetilde{\beta}_{ij})$ , with  $\widetilde{\beta}_{ij} = \beta_{\sigma(i),\sigma(j)}$ , has form

$$\widetilde{B} = \left(\begin{array}{cc} C & 0 \\ D & E \end{array}\right)$$

where C and E are  $l \times l$  and  $m \times m$  matrices respectively, and l + m = n.

Let  $C_e$  be an ergodic class and  $n_e$  be the number of ergodic states in  $C_e$ . Let  $A_e$  be the  $n_e \times n_e$  transition probability matrix within  $C_e$ . Then by (10)  $A_e$  is a *stochastic* matrix. Moreover,  $A_e$  is *irreducible*, since if  $A_e$  is *reducible*, then by some permutation  $\sigma$ ,  $A_e$  can be reduced to the form

$$\widetilde{A}_{e} = \begin{pmatrix} B_{e} & 0\\ C_{e} & D_{e} \end{pmatrix}, \qquad (12)$$

where  $B_e$  and  $D_e$  are  $k_e \times k_e$  and  $l_e \times l_e$  matrices respectively, with  $k_e + l_e = n_e$ . But

from (12), it can be seen that every state in  $\{\sigma(1), \ldots, \sigma(k_e)\}$  does not communicate with every state in  $\{\sigma(k_e + 1), \ldots, \sigma(n_e)\}$ , contradicting with the fact that  $C_e$  is a communicating class. Therefore,  $A_e$  must not be reducible.

Let  $C_t$  be a transient class and  $n_t$  be the number of transient states in  $C_t$ . Let  $A_t$  be the  $n_t \times n_t$  transition probability matrix within  $C_t$ . Then by (11),  $A_t$  is a *substochastic* matrix, that is, its individual row sums are  $\leq 1$ .

# 3 Relations between Communicating Classes and Stationary Probability Distributions of a Markov Chain

The next lemma shows the relation between irreducible Markov chains and irreducible transition probability matrices.

**Lemma 1** Let  $\{X_t\}$  be a Markov chain with a  $K \times K$  transition probability matrix A. Then  $\{X_t\}$  is irreducible if and only if A is irreducible.

### Proof :

Let  $\{X_t\}$  be a Markov chain with a  $K \times K$  transition probability matrix A. If  $\{X_t\}$  is irreducible, then it consists of a single communicating class C and the transition probability matrix within C is A. Since A is a stochastic matrix, then C is an ergodic class. From the ergodicity of C, the irreducibility of A follows.

On the otherhand, if A is irreducible, then from [1], page 63, for every  $1 \le i, j \le K$ , there is an integer n,  $0 \le n \le K$ , such that the (i, j) entry of  $A^n$  is positive. This means that every state communicates with each other. So the chain  $\{X_t\}$  is irreducible.

Let  $\{X_t\}$  be a Markov chain with a  $K \times K$  transition probability matrix A. Let  $K_e$  and  $K_t$  be the number of ergodic states and transient states respectively. In general, after a suitable permutation of indices, the transition probability matrix A can be written in the block form as

$$\widetilde{A} = \left( \begin{array}{cc} B & 0 \\ C & D \end{array} \right),$$

where B is a  $K_e \times K_e$ -stochastic matrix and D is a  $K_t \times K_t$ -substochastic matrix.

The block D describes the transient  $\rightarrow$  transient movements in the chain. For each class of transient states, at least one row in D will have sum < 1.

The  $K_t \times K_e$ -block C describes the transient  $\rightarrow$  ergodic movements in the chain. For each class of transient states, at least one row in C will have a non-zero entry.

Finally, The  $K_e \times K_e$ -block B describes the movements within each ergodic class in the chain. Suppose that the chain has e ergodic classes. Since it is impossible to leave an ergodic class, B has the form,

$$B = \begin{pmatrix} B_1 & 0 & \cdots & 0 \\ 0 & B_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & B_e \end{pmatrix},$$

where  $B_i$  is the transition matrix within the i-th ergodic class. For each i,  $B_i$  is an irreducible stochastic matrix.

The following lemma shows the relation between the communicating classes and the stationary probability distributions.

Lemma 2 Let  $\{X_t\}$  be a Markov chain with a  $K\times K$  transition probability matrix A. Let

$$S = \{\pi = (\pi_i) : \pi_i \ge 0, i = 1, \dots, K, \sum_{i=1}^{K} \pi_i = 1, \pi A = \pi\}$$
  

$$S^+ = \{\pi \in S : \pi_i > 0, i = 1, \dots, K\}$$
  

$$S^\circ = S - S^+.$$

- 1. If  $\{X_t\}$  is irreducible, then  $S = S^+$  and  $S^\circ = \emptyset$ .
- 2. If  $\{X_t\}$  has e communicating classes, with  $2 \le e \le K$  which all are ergodic, then  $S^+ \ne \emptyset$  and  $S^\circ \ne \emptyset$ .
- 3. If {X<sub>t</sub>} has k communicating classes, with  $2 \le k \le K$ , where e of them are ergodic,  $1 \le e < k$ , and t of them are transient, e + t = k, then  $S = S^{\circ}$  and  $S^+ = \emptyset$ .

Proof:

To prove (a), let  $\{X_t\}$  be an irreducible Markov chain. Suppose there is  $\pi \in S^\circ$ . Let k be the number of non-zero  $\pi_i$ . Without loss of generality, suppose that

$$\pi_i > 0,$$
 for  $i = 1, ..., k$   
 $\pi_i = 0,$  for  $i = k + 1, ..., K$ 

As  $\pi A = \pi$ , then

$$\alpha_{ij} = 0$$
, for  $i = 1, ..., K$ ,  $j = k + 1, ..., K$ .

Thus A has form

$$A = \left(\begin{array}{cc} B & 0 \\ C & D \end{array}\right),$$

where B is a  $k \times k$ -matrix and D is a  $(K - k) \times (K - k)$ -matrix. So A is reducible, contradicting with the fact that A is irreducible by Lemma 1. Therefore, it must be  $S^{\circ} = \emptyset$  and hence  $S = S^+$ .

To prove (b), let  $\{X_t\}$  be a Markov chain having e communicating classes with  $2 \le e \le K$ , which all are ergodic. Then without loss of generality, A is of the form

$$A = \begin{pmatrix} B_1 & 0 & \cdots & 0 \\ 0 & B_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & B_e \end{pmatrix},$$

where  $B_i$  is the transition matrix within the i-th ergodic class and it is an irreducible stochastic matrix.

Let  $\pi^i$  be an  $1 \times e_i$ -matrix, where  $e_i$  is the number of ergodic states in  $B_i$ , such that for  $i = 1, ..., e_i$ ,

$$\pi_{j}^{i} \geq 0, \quad j = 1, \dots, e_{i}, \quad \text{and} \quad \sum_{j=1}^{e_{i}} \pi_{j}^{i} = 1$$

and

$$\pi^{i}B_{i}=\pi^{i}.$$

By (a),

$$\pi_i^i > 0$$
, for  $j = 1, ..., e_i$  and  $i = 1, ..., e_i$ 

Let

$$\widehat{\pi} = (\pi^1, 0, \dots, 0),$$

then

$$\pi A = (\pi^1 B_1, 0, \dots, 0)$$
  
=  $(\pi^1, 0, \dots, 0)$ 
  
=  $\hat{\pi}$ .

So  $\widehat{\pi} \in S^{\circ}$  and hence  $S^{\circ} \neq \emptyset$ .

Let  $a_i$ ,  $i = 1, \dots, e$  be any real numbers such that

$$a_i > 0$$
,  $i = 1, \dots, e$  and  $\sum_{i=1}^e a_i = 1$ .

Let

$$\widetilde{\pi} = (a_1 \pi^1, a_2 \pi^2, \dots, a_e \pi^e),$$

then

$$\widetilde{\pi}_i > 0, \qquad {\rm for} \quad i=1,\ldots,K$$

and

$$\sum_{i=1}^{K} \widetilde{\pi}_{i} = \sum_{i=1}^{e} \sum_{j=1}^{e_{i}} \alpha_{i} \pi_{j}^{i}$$
$$= \sum_{i=1}^{e} \alpha_{i}$$
$$= 1.$$

Moreover,

$$\widetilde{\pi}A = (a_1\pi^1 B_1, a_2\pi^2 B_2, \dots, a_e\pi^e B_e)$$
  
=  $(a_1\pi^1, a_2\pi^2, \dots, a_e\pi^e)$   
=  $\widetilde{\pi}$ 

then  $\widetilde{\pi} \in S^+$  and hence  $S^+ \neq \emptyset$ .

To prove (c), let  $\{X_t\}$  be a Markov chain having k communicating classes,  $2 \le k \le K$ , where e of them are ergodic,  $1 \le e < k$ , and t of them are transient, e + t = k. Let  $K_e$  and  $K_t$  be the number of ergodic states and transient states of  $\{X_t\}$  respectively. Without loss of generality, assume that the matrix transition A is of the form

$$\mathsf{A} = \left(\begin{array}{cc} \mathsf{B} & \mathsf{0} \\ \mathsf{C} & \mathsf{D} \end{array}\right),$$

where B is a  $K_e \times K_e$  stochastic matrix, D is a  $K_t \times K_t$  substochastic matrix and C is a  $K_t \times K_e$  matrix,  $C \neq 0$ .

Let  $\pi = (\pi_1, \ldots, \pi_K) \in S$ , since

 $\pi A = \pi$ ,

then

or

 $\begin{array}{rcl} A^{\mathsf{T}}\pi^{\mathsf{T}} &=& \pi^{\mathsf{T}} \\ (A^{\mathsf{T}}-I_{\mathsf{K}})\pi^{\mathsf{T}} &=& 0 \end{array}$ 

$$\begin{pmatrix} B^{\mathsf{T}} - I_{\mathsf{K}_{e}} & \mathbf{C}^{\mathsf{T}} \\ 0 & D^{\mathsf{T}} - I_{\mathsf{K}_{t}} \end{pmatrix} \begin{pmatrix} \pi^{\mathsf{I}} \\ \pi^{\mathsf{2}} \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}, \qquad (13)$$

where  $\pi^1 = (\pi_1, \ldots, \pi_{K_e})$  and  $\pi^2 = (\pi_{K_e+1}, \ldots, \pi_K)$ . By (13),  $\pi^1$  and  $\pi^2$  satisfy

$$(B^{\mathsf{T}} - I_{\mathsf{K}_{e}})\pi^{1} + C^{\mathsf{T}}\pi^{2} = 0$$
(14)

$$(D^{\mathsf{T}} - I_{\mathsf{K}_{\mathsf{t}}})\pi^2 = 0.$$
 (15)

By [2], page 44,  $D^{\mathsf{T}} - I_{\mathsf{K}}$ , is invertible, so the only solution for (15) is  $\pi^2 = 0$ . So  $\pi$  must have form  $\pi = (\pi^1, 0)$ , where  $\pi^1$  satisfy (14). This means that  $\pi \in S^\circ$ . Therefore  $S \subset S^\circ$ , implying  $S = S^\circ$  and  $S^+ = \emptyset$ .

### Stationary Probability Distributions of a Markov Chain

32

## References

- [1] F.R. Gantmacher, Applications of the Theory of Matrices. New York: Interscience, 1959.
- [2] J.G. Kemeny and J.L. Snell. Finite Markov Chains, New York: Springer Verlag, 1976.